

Bernard: Fluid Dynamics

Vorticity and Vector Potential:

$$\nabla \times \underline{u} = \underline{\omega} \quad (1) \quad \underline{u} = u_r \hat{e}_r + u_\theta \hat{e}_\theta = \nabla \times \underline{A} \quad (2)$$

where $\underline{A} = \left(0, 0, \frac{\psi}{r \sin \theta}\right)$ is the vector potential.

For axisymmetric flow in spherical coordinates, note $\nabla \cdot \underline{A} = 0$.

$$\nabla \times (\nabla \times \underline{A}) = \underline{\omega} \quad (3)$$

In Helmholtz decomposition, i.e., $\nabla \underline{w} = \nabla \times \underline{A}$.

$$\nabla \times \left(\nabla \times \frac{\psi}{r \sin \theta} \hat{e}_\phi \right) = \underline{\omega} \quad (4)$$

Applying the curl operator in spherical coordinates:

$$-\frac{1}{r \sin \theta} L\psi \hat{e}_\phi = \omega_\phi \hat{e}_\phi$$

where the operator L is defined as:

$$L\psi = \psi_{rr} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \psi_\theta \right) \quad (5)$$

using definition curl in spherical coordinates or $\nabla^2 \left(\frac{\psi}{r \sin \theta} \right) \hat{e}_\phi$.

Proof

In axisymmetric spherical coordinates (r, θ, ϕ) , the vector potential \underline{A} is defined as:

$$\underline{A} = A_\phi \hat{e}_\phi = \frac{\psi}{r \sin \theta} \hat{e}_\phi$$

The vorticity $\underline{\omega}$ is given by the relation $\underline{\omega} = \nabla \times (\nabla \times \underline{A})$. We aim to show that:

$$\omega_\phi = -\frac{1}{r \sin \theta} L\psi, \quad \text{where } L\psi = \frac{\partial^2 \psi}{\partial r^2} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial \psi}{\partial \theta} \right)$$

1 Approach 1: Direct Curl Calculation

The velocity is defined as $\underline{u} = \nabla \times \underline{A}$. In spherical coordinates, for $\underline{A} = (0, 0, A_\phi)$:

$$\underline{u} = \frac{1}{r \sin \theta} \left[\frac{\partial}{\partial \theta} (A_\phi \sin \theta) \hat{e}_r - \frac{\partial}{\partial r} (r A_\phi) \hat{e}_\theta \right]$$

Substituting $A_\phi = \frac{\psi}{r \sin \theta}$:

$$u_r = \frac{1}{r^2 \sin \theta} \frac{\partial \psi}{\partial \theta}, \quad u_\theta = -\frac{1}{r \sin \theta} \frac{\partial \psi}{\partial r}$$

Now, calculate the vorticity $\underline{\omega} = \nabla \times \underline{u}$. For axisymmetric flow, only the ϕ -component survives:

$$\omega_\phi = \frac{1}{r} \left[\frac{\partial}{\partial r} (r u_\theta) - \frac{\partial u_r}{\partial \theta} \right]$$

Substituting the velocity components:

$$\begin{aligned}\omega_\phi &= \frac{1}{r} \left[\frac{\partial}{\partial r} \left(-\frac{1}{\sin\theta} \frac{\partial\psi}{\partial r} \right) - \frac{\partial}{\partial\theta} \left(\frac{1}{r^2 \sin\theta} \frac{\partial\psi}{\partial\theta} \right) \right] \\ &= -\frac{1}{r \sin\theta} \frac{\partial^2\psi}{\partial r^2} - \frac{1}{r^3} \frac{\partial}{\partial\theta} \left(\frac{1}{\sin\theta} \frac{\partial\psi}{\partial\theta} \right)\end{aligned}$$

Factoring out $-\frac{1}{r \sin\theta}$ yields the desired operator L :

$$\omega_\phi = -\frac{1}{r \sin\theta} \left[\frac{\partial^2\psi}{\partial r^2} + \frac{\sin\theta}{r^2} \frac{\partial}{\partial\theta} \left(\frac{1}{\sin\theta} \frac{\partial\psi}{\partial\theta} \right) \right] = -\frac{1}{r \sin\theta} L\psi$$

2 Approach 2: Vector Laplacian Identity

For a solenoidal vector field ($\nabla \cdot \underline{A} = 0$), we use the identity:

$$\nabla \times (\nabla \times \underline{A}) = -\nabla^2 \underline{A}$$

In curvilinear coordinates, the ϕ -component of the vector Laplacian is:

$$(\nabla^2 \underline{A})_\phi = \nabla^2 A_\phi - \frac{A_\phi}{r^2 \sin^2\theta}$$

Expanding the scalar Laplacian $\nabla^2 A_\phi$ and substituting $A_\phi = \frac{\psi}{r \sin\theta}$:

$$\begin{aligned}\nabla^2 \left(\frac{\psi}{r \sin\theta} \right) &= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \frac{\psi}{r \sin\theta} \right) + \frac{1}{r^2 \sin\theta} \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial}{\partial\theta} \frac{\psi}{r \sin\theta} \right) \\ &= \frac{1}{r \sin\theta} \frac{\partial^2\psi}{\partial r^2} + \frac{1}{r^3 \sin\theta} \frac{\partial}{\partial\theta} \left(\frac{\partial\psi}{\partial\theta} - \psi \cot\theta \right)\end{aligned}$$

After collecting terms and subtracting $\frac{\psi}{r^3 \sin^3\theta}$, the expression simplifies to:

$$-\nabla^2 \underline{A} = -\frac{1}{r \sin\theta} \left[\psi_{rr} + \frac{1}{r^2} \psi_{\theta\theta} - \frac{\cot\theta}{r^2} \psi_\theta \right] \hat{e}_\phi = -\frac{1}{r \sin\theta} L\psi \hat{e}_\phi$$

This confirms that $\omega_\phi \hat{e}_\phi = \nabla^2 \left(\frac{\psi}{r \sin\theta} \right) \hat{e}_\phi$ as noted in the derivation.

Stokes Flow: $\nabla^2 \underline{\omega} = 0$

$$\nabla \times \nabla \times \underline{\omega} = \nabla(\nabla \cdot \underline{\omega}) - \nabla^2 \underline{\omega}$$

Since $\nabla \cdot \underline{\omega} = 0$:

$$\begin{aligned}\nabla \times (\nabla \times \underline{\omega}) &= 0 = -\nabla^2 \underline{\omega} \\ \nabla \times (\nabla \times \omega_\phi \hat{e}_\phi) &= 0 = -\nabla^2 \omega_\phi \hat{e}_\phi \\ \nabla \times \left(\nabla \times \frac{-L\psi}{r \sin\theta} \hat{e}_\phi \right) &= 0 = -\nabla^2 \omega_\phi \hat{e}_\phi\end{aligned}$$

We previously established the identity (4), which states that for any scalar function f :

$$\nabla \times \left(\nabla \times \frac{f}{r \sin\theta} \hat{e}_\phi \right) = -\frac{1}{r \sin\theta} L(f) \hat{e}_\phi$$

By choosing $f = L\psi$ (noting that $\omega_\phi \propto L\psi$), we substitute this into the Stokes flow condition:

$$\nabla \times \left(\nabla \times \left[\frac{-L\psi}{r \sin \theta} \hat{e}_\phi \right] \right) = -\frac{1}{r \sin \theta} L(-L\psi) \hat{e}_\phi = 0$$

This leads directly to the fourth-order governing equation for the stream function:

$$L(L\psi) = 0 \quad \text{or} \quad L^2\psi = 0$$

Expanding the operator:

$$\left[\frac{\partial^2}{\partial r^2} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \right) \right]^2 \psi = 0$$

Boundary Conditions (BC):

- **No-slip at surface:** $(u_r, u_\theta) = (0, 0)$ at $r = a$
- i.e., $\psi_\theta(a, \theta) = 0$ and $\psi_r(a, \theta) = 0$
- **Uniform flow at infinity:** As $r \rightarrow \infty$, $\psi = \frac{1}{2}Ur^2 \sin^2 \theta$

Velocity Relations:

$$u_r = \frac{\psi_\theta}{r^2 \sin \theta}, \quad u_\theta = \frac{-\psi_r}{r \sin \theta}$$