

## Statement to prove

Let  $\boldsymbol{\tau}$  be the viscous stress tensor of an incompressible Newtonian fluid,

$$\boldsymbol{\tau} = \mu (\nabla \mathbf{u} + (\nabla \mathbf{u})^T), \quad \boldsymbol{\omega} = \nabla \times \mathbf{u}$$

Then

$\mathbf{n} \cdot \boldsymbol{\tau} = -\mu \mathbf{n} \times \boldsymbol{\omega} \quad (\text{tangential component})$

## Proof (index notation, rigorous)

Write everything in components.

Let  $n_i$  be the components of  $\mathbf{n}$ .

### 1. Left-hand side

$$(\mathbf{n} \cdot \boldsymbol{\tau})_i = n_j \tau_{ji} = \mu n_j (\partial_j u_i + \partial_i u_j) \quad (1)$$

### 2. Use vorticity identity

Vorticity components:

$$\omega_k = \varepsilon_{klm} \partial_l u_m$$

Compute the cross product:

$$(\mathbf{n} \times \boldsymbol{\omega})_i = \varepsilon_{ijk} n_j \omega_k = \varepsilon_{ijk} n_j \varepsilon_{klm} \partial_l u_m$$

Use

$$\varepsilon_{ijk} \varepsilon_{klm} = \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}$$

So

$$(\mathbf{n} \times \boldsymbol{\omega})_i = n_j \partial_i u_j - n_j \partial_j u_i \quad (2)$$


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### 3. Combine (1) and (2)

From (1),

$$(\mathbf{n} \cdot \boldsymbol{\tau})_i = \mu (n_j \partial_j u_i + n_j \partial_i u_j)$$

Using (2),

$$n_j \partial_i u_j = (\mathbf{n} \times \boldsymbol{\omega})_i + n_j \partial_j u_i$$

Substitute:

$$(\mathbf{n} \cdot \boldsymbol{\tau})_i = \mu [2 n_j \partial_j u_i + (\mathbf{n} \times \boldsymbol{\omega})_i]$$


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#### 4. Extract the tangential part

The term  $n_j \partial_j u_i$  is **normal to the surface** (rate of change along  $\mathbf{n}$ ).

Therefore, the **tangential component** of  $\mathbf{n} \cdot \boldsymbol{\tau}$  is

$$(\mathbf{n} \cdot \boldsymbol{\tau})_t = -\mu (\mathbf{n} \times \boldsymbol{\omega})$$

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#### Final result (precise form)

$$(\mathbf{n} \cdot \boldsymbol{\tau})_{\tan} = -\mu \mathbf{n} \times \boldsymbol{\omega}, \quad \mathbf{n} \cdot (\mathbf{n} \cdot \boldsymbol{\tau}) = 0$$

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#### Why your original equation was confusing

- $\boldsymbol{\tau}$ : second-order tensor
- $\mathbf{n} \cdot \boldsymbol{\tau}$ : vector (traction)
- $\mathbf{n} \times \boldsymbol{\omega}$ : vector

So the **correct, dimensionally consistent identity** is the **tangential projection** of  $\mathbf{n} \cdot \boldsymbol{\tau}$ , not the full vector.

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If you want, I can now:

- rewrite this in **compact tensor form** suitable for a journal, or
- align it exactly with **wall shear stress definitions** used in CFDShip-Iowa.