Chapter 6 Introduction Incompressible Turbulent Flow

3. Basic Concepts

Most flows in engineering are turbulent: flows over vehicles (airplane, ship, train, car), internal flows (heating and ventilation, turbomachinery), and geophysical flows (atmosphere, ocean).

V(x, t) and p(x, t) are random functions of space and time, but statistically stationary flows such as steady and forced or dominant frequency unsteady flows display coherent features and are amendable to statistical analysis, i.e. time, space, ensemble, or conditional averaging. RMS and other low-order statistical quantities can be modeled and used in conjunction with the averaged equations for solving practical engineering problems.

Turbulent motions range in size from the characteristic width in the flow δ to much smaller scales, which become progressively smaller as the Re = $U\delta/\upsilon$ increases.





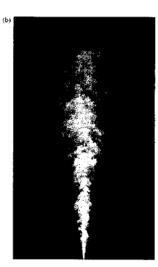


Fig. 1.2. Planar images of concentration in a turbulent jet: (a) Re = 5,000 and (b) Re = 20,000. From Dahm and Dimotakis (1990) .

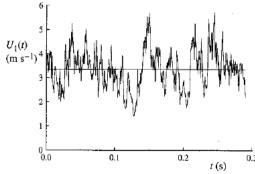
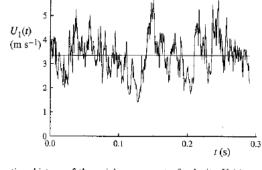


Fig. 1.3. The time history of the axial component of velocity $U_1(t)$ on the centerline of a turbulent jet. From the experiment of Tong and Warhaft (1995).



1.0 $\frac{\langle U_1 \rangle}{\langle U_1 \rangle_0}$ 0.0 -0.2 0.0 0.2 x_2 / x_1

Fig. 1.4. The mean axial velocity profile in a turbulent jet. The mean velocity (U_1) is normalized by its value on the centerline, $\langle U_1 \rangle_0$; and the cross-stream (radial) coordinate x_2 is normalized by the distance from the nozzle x_1 . The Reynolds number is 95,500. Adapted from Hussein, Capp, and George (1994).

Fig. 1.1. A photograph of the turbulent plume from the ground test of a Titan IV rocket motor. The nozzle's exit diameter is 3m, the estimated plume height is 1,500 m, and the estimated Reynolds number is 200×10^6 . For more details see Mungal and Hollingsworth (1989). With permission of San Jose Mercury & News.

a. Randomness and fluctuations:

Turbulence is irregular, chaotic, and unpredictable. However, for statistically stationary flows, such as steady flows, can be analyzed using Reynolds's decomposition.

$$u = u + u'$$
 $u = \frac{1}{T} \int_{t_0}^{t_0+T} u \, dT$ $u' = 0$ $u''^2 = \frac{1}{T} \int_{t_0}^{t_0+T} u'^2 \, dT$ etc.

 \bar{u} = mean motion

u' = superimposed random fluctuation

 $\overline{u}^{\prime 2}$ = Reynolds stresses = mean square u^{\prime} = variance u

 $\sqrt{\overline{u}^{'2}}$ = RMS u' = standard deviation (SD) u

SD%Mean = coefficient of variation= $\sqrt{\overline{u}^{'2}}/\overline{u}$

Triple decomposition is used for forced or dominant frequency flows.

$$u = u + u'' + u'$$

Where u'' = organized oscillation

b. Nonlinearity

Reynolds stresses and 3D vortex stretching are direct result of nonlinear nature of turbulence. In fact, Reynolds stresses arise from nonlinear convection term after substitution of Reynolds decomposition into NS equations and time averaging.

c. Diffusion

Large scale mixing of fluid particles greatly enhances diffusion of momentum (and heat), i.e.,

Reynolds Stresses:
$$-\rho \overline{u'_i u'_j} >> \overline{\tau_{ij} = \mu \varepsilon_{ij}}$$

Isotropic eddy viscosity:
$$-\overline{u'_i u'_j} = v_t \varepsilon_{ij} - \frac{2}{3} \delta_{ij} k$$

d. Vorticity/eddies/energy cascade

Turbulence is characterized by flow visualization as eddies, which vary in size from the largest L_{δ} (width of flow) to the smallest L_K. The largest eddies have velocity scale U and time scale L_{δ}/U .

The orders of magnitude of the smallest eddies (Kolmogorov scale) are:

$$L_{K}$$
 = Kolmogorov micro-scale = $\left[\frac{\upsilon^{3}\delta}{U^{3}}\right]^{\frac{1}{4}} = \left[\frac{\upsilon^{3}}{\varepsilon}\right]^{\frac{1}{4}}$

$$L_K = O(mm) >> L_{mean free path} = 6 \times 10^{-8} m$$

Velocity scale = $(v\epsilon)^{1/4} = O(10^{-2}m/s)$
Time scale = $(v/\epsilon)^{1/2} = O(10^{-2}s)$

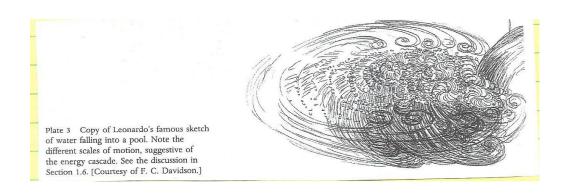
IIHR wave basin experiments
$$L_{K}\approx .1 \text{ - .5 mm, i.e.,}$$

$$100-500~\mu\text{m.}$$

$$17\text{-}181~\mu\text{m}\approx D_{\text{hair}}$$

Largest eddies contain most of energy, which break up into successively smaller eddies with energy transfer to yet smaller eddies until L_K is reached and energy is dissipated by molecular viscosity. Richardson (1922):

- Big whorls have little whorls. Lδ
 - Which feed on their velocity.
 - And little whorls have lesser whorls,
- And so on to viscosity (in the molecular sense). L_{K}



e. Dissipation

$$\ell_0 = L_{\delta}$$

$$u_0 = \sqrt{k} \qquad k = \overline{u'^2} + \overline{v'^2} + \overline{w'^2}$$

$$= 0(U)$$

$$Re_{\delta} = u_0 \ell_0 / v = large$$

Energy comes from largest scales and fed by mean motion

 ε = rate of dissipation = energy/time

$$=\frac{u_0^2}{\tau_o} \qquad \qquad \tau_o = \frac{\ell_0}{u_0} = \text{eddies turn over time}$$

Dissipation occurs at smallest scales

$$= \frac{u_0^3}{l_0} \qquad \text{independent } \mathbf{U} \qquad L_K = \left[\frac{v^3}{\varepsilon}\right]^{\frac{1}{4}}$$

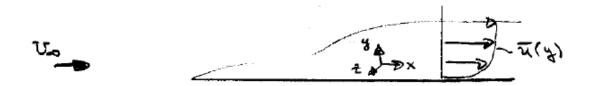
$$L_K = \left[\frac{\upsilon^3}{\varepsilon}\right]^{\frac{1}{4}}$$

Dissipation rate is determined by the large-scale dynamics and not f(v).

The smallest scales are only $f(\varepsilon, v)$, e.g., length scale L_K .

f. Examples Experimental Data for Wall Flows

Fig. below shows measurements of turbulence for $Re_x=10^7$.

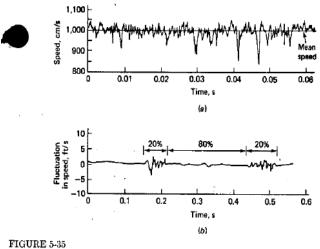


Note the following mean-flow features:

- (1) Fluctuations are large ~ 11% U_∞
- (2) Presence of wall causes anisotropy, i.e., the fluctuations differ in magnitude due to geometric and physical reasons. $\overline{u'^2}$ is largest, $\overline{v'^2}$ is smallest and reaches its maximum much further out than $\overline{u'^2}$ or $\overline{w'^2}$. $\overline{w'^2}$ is intermediate in value.
- (3) $\overline{u'v'} \neq 0$ and, as will be discussed, plays a very important role in the analysis of turbulent shear flows.

- (4) Although $\overline{u_i u_j} = 0$ at the wall, it maintains large values right up to the wall
- (5) Turbulence extends to $y > \delta$ due to intermittency. The interface at the edge of the boundary layer is called the superlayer. This interface undulates randomly between fully turbulent and non-turbulent flow regions. The mean position is at $y \sim 0.78 \ \delta$.
- (6) Fluctuating normal velocities equal and $u_iu_j = 0$ $i \neq j$ at high frequencies (isotropic behavior). All five spectra have same frequency range.
- (7) Near wall turbulent wave number spectra have more energy, i.e., small λ , whereas near δ large eddies dominate.

Wavenumber k: $k = \frac{2\pi}{\lambda}$



Hot-wire measurements showing turbulent velocity fluctuations: (a) typical trace of a single velocity component in a turbulent flow; (b) trace showing intermittent turbulence at the edge of a jet.

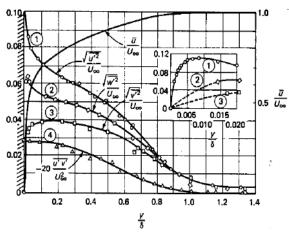
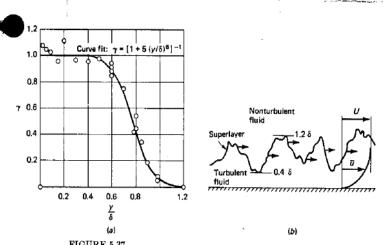
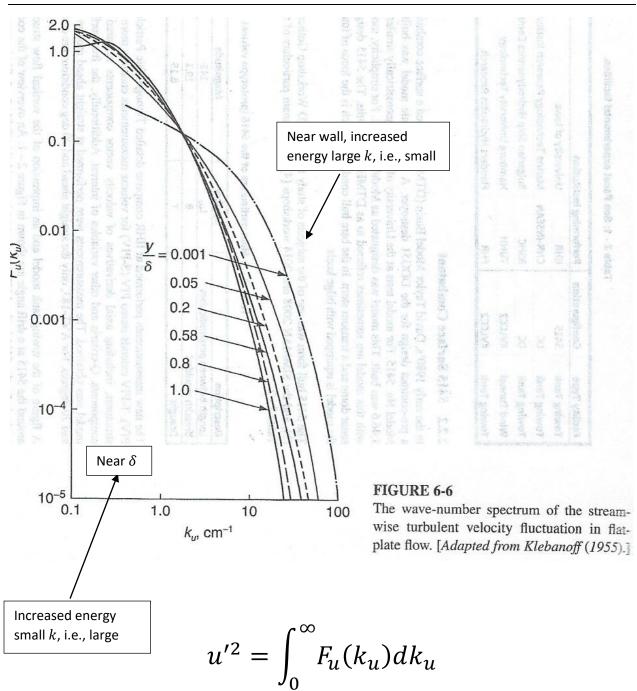


FIGURE 5-36 ; Flat-plate measurements of the fluctuating velocities u' (streamwise), v' (normal), and w' (lateral) and the turbulent shear u'v'. [After Klebanoff (1965).]



The phenomenon of intermittency in a turbulent boundary layer: (a) measured intermittency factors [after Klebanoff (1955)]; (b) the superlayer interface between turbulent and nonturbulent fluid.



 u'^2 = total mean-square fluctuation.

 $F_u(k_u) = 1D$ spatial energy spectrum.

Averages:

For turbulent flow $\underline{V}(\underline{x}, t)$, $p(\underline{x}, t)$ are random functions of time and must be evaluated statistically using averaging techniques: time, ensemble, phase, or conditional.

Time Averaging

For stationary flow, the mean is not a function of time, and we can use time averaging.

$$\frac{1}{u} = \frac{1}{T} \int_{t_0}^{t_0+t} u(t) dt \quad T > \text{any significant period of } u' = u - u$$

(e.g. 1 sec. for wind tunnel and 20 min. for ocean)

Ensemble Averaging

For non-stationary flow, the mean is a function of time and ensemble averaging is used

$$\overline{u}(t) = \frac{1}{N} \sum_{i=1}^{N} u^i(t)$$
 N is large enough that \overline{u} independent

 $u^{i}(t)$ = collection of experiments performed under identical conditions (also can be phase aligned for same t=0).

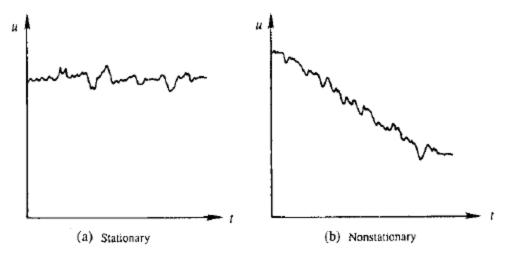


Fig. 12.2 Stationary and nonstationary time series.

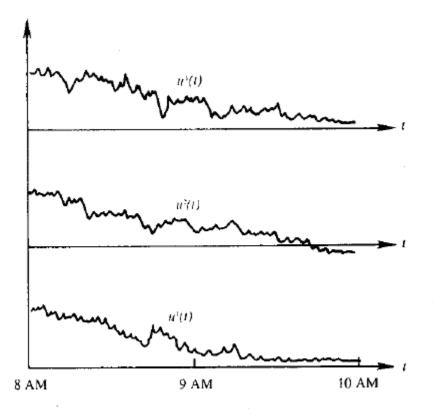


Fig. 12.3 An ensemble of functions u(t).

Phase and Conditional Averaging

Like ensemble averaging, but for flows with dominant frequency content or other condition, which is used to align time series for some phase/condition. In this case triple velocity decomposition is used: $u = \overline{u} + u'' + u'$ where u'' is called organized oscillation. Phase/conditional averaging extracts all three components.

Averaging Rules:

$$f = \overline{f} + f'$$
 $g = \overline{g} + g'$ $s = x \text{ or } t$

$$\overline{f}' = 0$$
 $\overline{\overline{f}} = \overline{f}$ $\overline{f}' \overline{g} = \overline{f} \overline{g}$ $\overline{f'} \overline{g} = 0$

$$\overline{f+g} = \overline{f} + \overline{g} \qquad \qquad \frac{\overline{\partial f}}{\partial s} = \frac{\partial \overline{f}}{\partial s} \qquad \qquad \overline{fg} = \overline{f} \, \overline{g} + \overline{f'g'}$$

$$\overline{\int f \ ds} = \int \overline{f} \ ds$$

Reynolds-Averaged Navier-Stokes Equations

For convenience of notation use uppercase for mean and lowercase for fluctuation in Reynolds's decomposition.

$$\begin{array}{l} \overset{\sim}{u_{i}} = U_{i} + u_{i} \\ \tilde{p} = P + p \\ \\ \frac{\partial \overset{\sim}{u_{i}}}{\partial x_{i}} = 0 \\ \frac{\partial \overset{\sim}{u_{i}}}{\partial t} + \overset{\sim}{u_{j}} \frac{\partial \overset{\sim}{u_{i}}}{\partial x_{j}} = -\frac{1}{\rho} \frac{\partial \tilde{p}}{\partial x_{i}} + v \frac{\partial^{2} \overset{\sim}{u_{i}}}{\partial x_{j} \partial x_{j}} - g \delta_{i3} \end{array} \qquad \begin{array}{l} \text{Instantaneous} \\ \text{NS} \\ \text{equation} \end{array}$$

Mean Continuity Equation

$$\frac{\overline{\partial}_{i}(U_{i} + u_{i})}{\partial x_{i}} = \frac{\partial U_{i}}{\partial x_{i}} + \frac{\partial \overline{u}_{i}}{\partial x_{i}} = \frac{\partial U_{i}}{\partial x_{i}} = 0$$

$$\frac{\partial u}{\partial x_{i}} = \frac{\partial U_{i}}{\partial x_{i}} + \frac{\partial u_{i}}{\partial x_{i}} = 0$$

$$\frac{\partial u}{\partial x_{i}} = 0$$

Both mean and fluctuation satisfy divergence = 0 condition.

Mean Momentum Equation

$$\frac{\partial}{\partial t}(U_i + u_i) + (U_j + u_j)\frac{\partial}{\partial x_j}(U_i + u_i) = -\frac{1}{\rho}\frac{\partial}{\partial x_i}(P + p) + \nu \frac{\partial^2}{\partial x_j x_j}(U_i + u_i) - g\delta_{i3}$$

$$\frac{\partial}{\partial t}(U_{i}+u_{i}) = \frac{\partial U_{i}}{\partial t} + \frac{\partial \overline{u}_{i}}{\partial t} = \frac{\partial U_{i}}{\partial t}$$

$$(U_{j} + u_{j}) \frac{\partial}{\partial x_{j}} (U_{i} + u_{i}) = U_{j} \frac{\partial U_{i}}{\partial x_{j}} + U_{j} \frac{\partial \overline{u_{i}}}{\partial x_{j}} + \overline{u_{j}} \frac{\partial U_{i}}{\partial x_{j}} + \overline{u_{j}} \frac{\partial u_{i}}{\partial x_{j}}$$

$$= U_{j} \frac{\partial U_{i}}{\partial x_{j}} + \frac{\partial}{\partial x_{j}} \overline{u_{i}} \overline{u_{j}}$$
Since
$$\frac{\partial}{\partial x_{i}} \overline{u_{i}} \overline{u_{j}} = \overline{u_{j}} \frac{\partial u_{j}}{\partial x_{i}} + \overline{u_{j}} \frac{\partial u_{i}}{\partial x_{i}} = \overline{u_{j}} \frac{\partial u_{i}}{\partial x_{i}}$$

$$\frac{\overline{\partial}}{\partial x_{i}}(P+p) = \frac{\partial P}{\partial x_{i}} + \frac{\partial \overline{p}}{\partial x_{i}} = \frac{\partial P}{\partial x_{i}}$$

$$-\overline{g\delta_{i3}} = -g\delta_{i3}$$

$$\overline{\upsilon\frac{\partial^{2}}{\partial x_{j}^{2}}(U_{i}+u_{i})} = \upsilon\frac{\partial^{2}U_{i}}{\partial x_{j}^{2}} + \upsilon\frac{\partial^{2}\overline{u}_{i}}{\partial x_{j}^{2}} = \upsilon\frac{\partial^{2}U_{i}}{\partial x_{j}^{2}}$$

$$\frac{\partial U_i}{\partial t} + U_j \frac{\partial U_i}{\partial x_j} + \frac{\partial (\overline{u_i u_j})}{\partial x_j} = -\frac{1}{\rho} \frac{\partial P}{\partial x_i} + \upsilon \frac{\partial^2}{\partial x_j^2} U_i - g \delta_{i3}$$

Or
$$\frac{DU_i}{Dt} = -\frac{1}{\rho} \frac{\partial P}{\partial x_i} - g \delta_{i3} + \frac{\partial}{\partial x_j} \left[\upsilon \frac{\partial U_i}{\partial x_j} - \overline{u_i u_j} \right]$$

Or
$$\frac{DU_i}{Dt} = -g\delta_{i3} + \frac{1}{\rho} \frac{\partial}{\partial x_j} \overline{\sigma}_{ij}$$

$$\overline{\sigma}_{ij} = -P\delta_{ij} + \mu \left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) - \rho \overline{u_i u_j}$$
RANS
Equations
with $\frac{\partial U_i}{\partial x_j} = 0$

The difference between the NS and RANS equations is the Reynolds stresses $-\rho \overline{u_i u_j}$, which acts like an additional stress.

 $-\rho u_i u_i = -\rho u_i u_i$ (i.e., Reynolds stresses are symmetric)

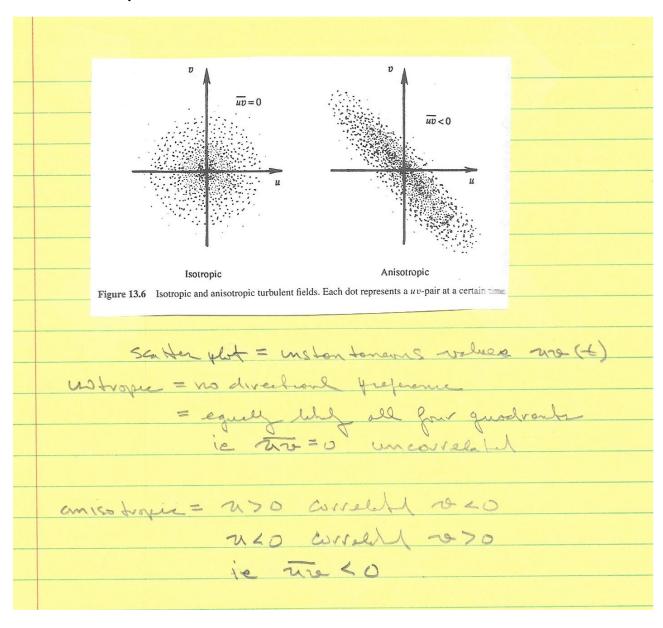
$$\begin{bmatrix} -\rho\overline{u^2} & -\rho\overline{u}\overline{v} & -\rho\overline{u}\overline{w} \\ -\rho\overline{v}\overline{u} & -\rho\overline{v^2} & -\rho\overline{v}\overline{w} \\ -\rho\overline{w}\overline{u} & -\rho\overline{w}\overline{v} & -\rho\overline{w^2} \end{bmatrix} = \begin{bmatrix} -\rho\overline{u^2} & -\rho\overline{u}\overline{v} & -\rho\overline{u}\overline{w} \\ -\rho\overline{u}\overline{v} & -\rho\overline{v}\overline{v} & -\rho\overline{v}\overline{w} \\ -\rho\overline{u}\overline{w} & -\rho\overline{w}\overline{w} & -\rho\overline{w}^2 \end{bmatrix}$$

 $\overline{u_i^2}$ are normal stresses.

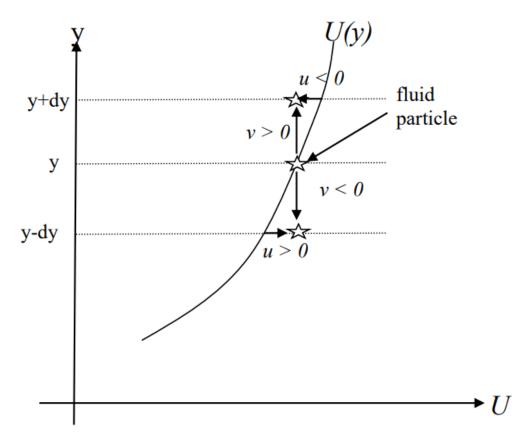
 $u_i u_j$ $i \neq j$ are shear stresses.

6 new unknowns

For homogeneous/isotropic turbulence $\overline{u_iu_j}$ $i \neq j = 0$ and $\overline{u^2} = \overline{v^2} = \overline{w^2} = \text{constant}$; however, turbulence is generally non-isotropic.



Consider shear flow with $\frac{dU}{dy} > 0$ as below,



The fluid velocity is: $\underline{V} = (U + u, v, w)$

If fluid particle retains its total velocity \underline{V} from y to $y \pm dy$ gives, $U + u = constant \rightarrow \text{If } U$ increases, u decreases and vice versa.

$$\begin{array}{cccc}
v > 0 & \rightarrow & u < 0 \\
v < 0 & \rightarrow & u > 0
\end{array}
\qquad \qquad \overline{uv} < 0$$

x-momentum tends towards decreasing y as turbulence diffuses gradients and decreases $\frac{dU}{dv}$

x-momentum transport in y direction, i.e., across y = constant AA per unit area

$$M_{xy} = \int \rho \tilde{u} \underline{V} \cdot \underline{n} \, dA$$
, where $\tilde{u} = (U + u)$

$$\frac{d\overline{M_{xy}}}{dA} = \rho \overline{(U+u)v} = \rho U \overline{v} + \rho \overline{uv} = \rho \overline{uv}$$

i.e., $\rho \overline{u_i u_j}$ = average flux of j-momentum in i-direction = average flux of i-momentum in j-direction

Closure Problem:

- 1. RANS equations differ from the NS equations due to the Reynolds stress terms.
- 2. RANS equations are for the mean flow (U_i, P) ; thus, represent 4 equations with 10 unknowns due to the additional 6 unknown Reynolds stresses $\overline{u_i u_i}$
- 3. Equations can be derived for $\overline{u_iu_j}$ by adding together and averaging the NS for U_i multiplied by u_j and for U_j multiplied by u_i , but these include additional unknows, i.e., diffusion of the pressure work terms and turbulent flux of the Reynolds stresses (triple products $\overline{u_iu_ju_l}$), dissipation rate tensor, and pressure rate-of-strain tensor.
- 4. Equations, e.g., for triple products can be derived that involve higher order correlations leading to fact that RANS equations are inherently non-deterministic, which requires turbulence modeling.
- 5. Turbulence closure models render deterministic RANS solutions.
- 6. The NS and RANS equations have paradox that NS equations are deterministic but have nondeterministic solutions for turbulent flow due to inherent stochastic nature of turbulence, whereas the RANS equations are nondeterministic, but have deterministic solutions due to turbulence closure models.

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Note that differential instantaneous mechanical energy equation has $-\phi$ term where $\phi \ge 0$ = rate of viscous dissipation = loss of mechanical energy due to deformation of fluid particle; and recall differential energy equation has $+\phi$ term, i.e., gain in internal energy due ϕ . See Chapters 3&4 Part 1 page 60.

Turbulent Kinetic Energy Equation

$$k = \frac{1}{2}\overline{u_i^2} = \frac{1}{2}\left(\overline{u^2} + \overline{v^2} + \overline{w^2}\right)$$
 = turbulent kinetic energy

$$\overset{\sim}{u_i} = U_i + u_i$$

$$p = P + p$$

Subtracting NS equation for u_i and RANS equation for U_i results in equation for u_i :

$$\frac{\partial u_i}{\partial t} + U_j \frac{\partial u_i}{\partial x_j} + u_j \frac{\partial U_i}{\partial x_j} + u_j \frac{\partial u_i}{\partial x_j} - \frac{\partial}{\partial x_j} (\overline{u_i u_j}) = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} + \upsilon \frac{\partial^2 u_i}{\partial x_j^2}$$

Multiply by u_i and time average

$$\frac{Dk}{Dt} = \underbrace{-\frac{1}{\rho} \frac{\partial}{\partial x_{j}} \overline{pu_{j}}}_{I} - \underbrace{\frac{1}{2} \frac{\partial}{\partial x_{j}} \overline{u_{i}^{2} u_{j}}}_{II} + \underbrace{2v \frac{\partial}{\partial x_{j}} \overline{u_{i} e_{ij}}}_{III} - \underbrace{\frac{\partial U_{i}}{\partial x_{j}} \frac{\partial U_{i}}{\partial x_{j}}}_{IV}$$

Where
$$\frac{Dk}{Dt} = \frac{\partial k}{\partial t} + U_j \frac{\partial k}{\partial x_j}$$
 and $e_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$

I = pressure transport

II= turbulent transport

III=viscous diffusion

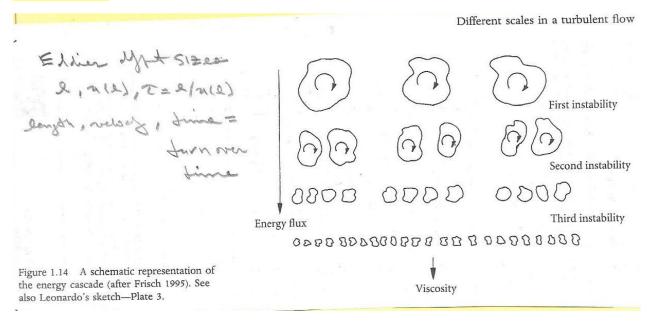
IV = shear production (usually > 0) represents loss of mean kinetic energy and gain of turbulent kinetic energy due to

interactions of
$$\overline{u_iu_j}$$
 and $\frac{\partial U_i}{\partial x_j}$

 $V = viscous dissipation = \varepsilon$

VI= turbulent convection

Recall previous discussions of energy cascade and dissipation: Energy fed from mean flow to largest eddies and cascades to smallest eddies via inviscid processes where dissipation takes place. According to Kolmogorov hypotheses after about 6 reductions in size the turbulence becomes isotropic.



Kinetic energy = $k \approx u_o^2$

$$au_0=rac{l_0}{u_0}= ext{turn over time}.$$

$$\varepsilon = \frac{u_0^2}{\tau_0} = \frac{u_0^3}{l_0}$$

 $I_0 = L_\delta$ = width of flow (i.e., size of largest eddy)

Kolmogorov Hypothesis:

- (1) local isotropy: for large Re, micro-scale $\ell << \ell_0$ and turbulence structures are isotropic.
- (2) first similarity: for large Re, micro-scale has universal form uniquely determined by v and ϵ : universal equilibrium range.

$$\eta = (\upsilon^3 / \varepsilon)^{1/4}$$
 length $\eta / l_0 = \text{Re}^{-3/4}$

$$u_{\eta} = (\varepsilon \upsilon)^{1/4}$$
 velocity $u_{\eta} / u_0 = \text{Re}^{-1/4}$

$$au_{\eta} = (\upsilon/\varepsilon)^{1/2}$$
 time $au_{\eta}/ au_0 = \mathrm{Re}^{-1/2}$

Also shows that as Re increases, the range of scales increase.

- (3) second similarity: for large Re, intermediate scale has a universal form uniquely determined by ϵ and independent of ν : inertial subrange.
- (1) (3) are called universal equilibrium range in distinction from non-isotropic energy-containing range.

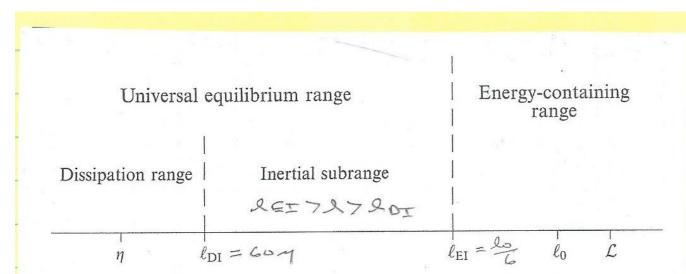


Fig. 6.1. Eddy sizes ℓ (on a logarithmic scale) at very high Reynolds number, showing the various lengthscales and ranges.

Spectrum of turbulence in the inertial subrange $S=S(k,\epsilon)$

$$\overline{u^2} = \int_0^\infty S(k) dk$$
 $k = 2\pi/\lambda = \text{wave number.}$

 $S=A\varepsilon^{2/3}k^{-5/3}$ for $l_0^{-1}<< k<< \eta^{-1}$ (based on dimensional analysis) where A = Kolmogorov universal constant = 1.5 and $S=A\varepsilon^{2/3}k^{-5/3}$ called Kolmogorov k^{-5/3} law.

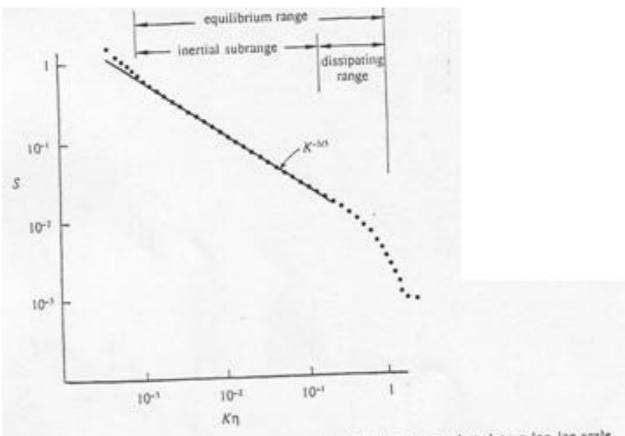


Fig. 12.12 A typical wavenumber spectrum observed in the ocean, plotted on a log-log scale. The unit of S is arbitrary, and the dots represent hypothetical data.

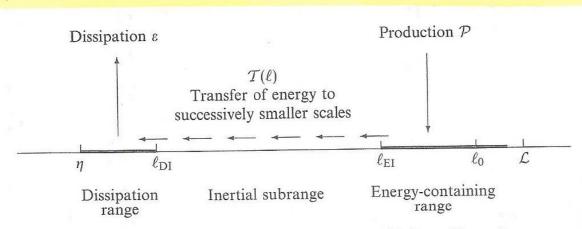


Fig. 6.2. A schematic diagram of the energy cascade at very high Reynolds number.

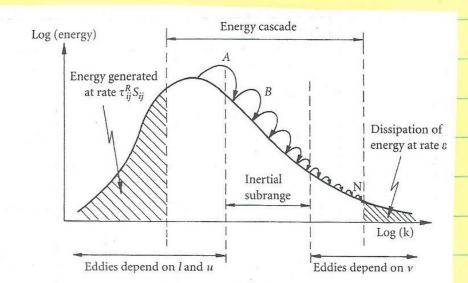
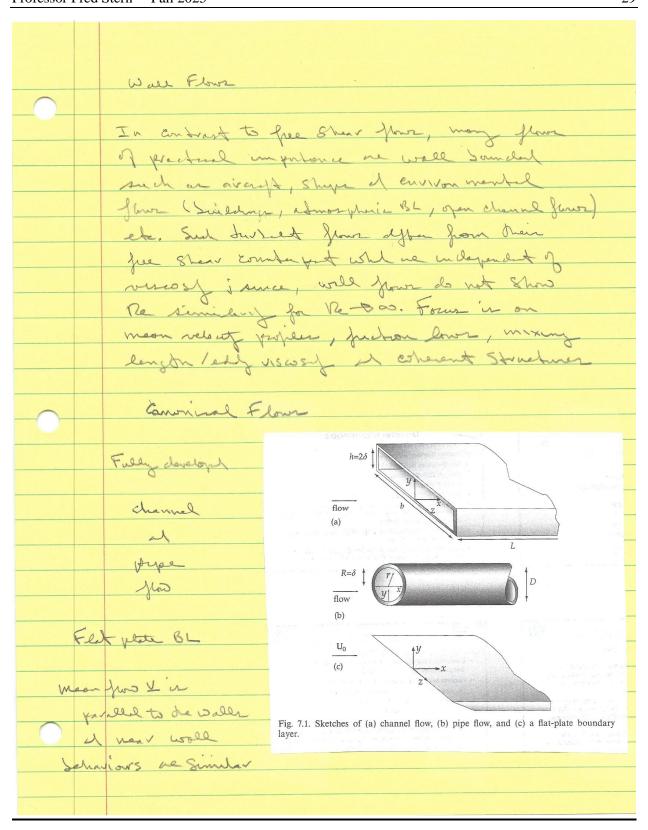
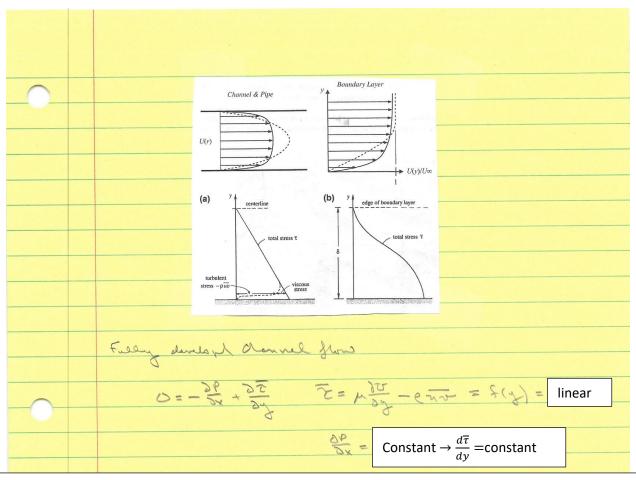


Figure 5.3 Schematic representation of the energy cascade.





Very near the wall the viscous stress $\mu \frac{\partial U}{\partial y}$ dominates, whereas away from the wall the turbulent stress $-\rho \overline{uv}$ dominates and they combine such that the total shear stress is linear between the wall and the channel/pipe centerline; and symmetric across the entire channel/pipe.

Flat plate BL	
$evox + evox = \frac{1}{2}$ $\overline{C} = f(x,y)$	
the state of the s	

Velocity Profiles: Inner, Outer, and Overlap Layers

Detailed examination of turbulent boundary layer velocity profiles indicates the existence of a three-layer structure:

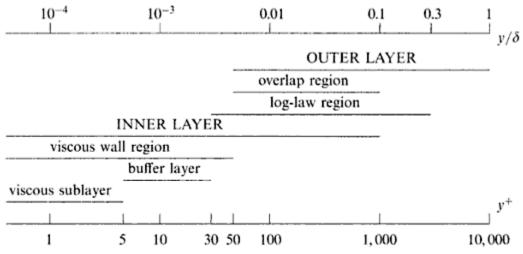


Fig. 7.8. A sketch showing the various wall regions and layers defined in terms of $y^+ = y/\delta_v$ and y/δ , for turbulent channel flow at high Reynolds number (Re_t = 10⁴).

- (1) A thin inner layer close to the wall, which is governed by molecular viscous scales, and independent of boundary layer thickness δ , freestream velocity U_e and pressure gradient.
- (2) An outer layer where the flow is governed by turbulent shear stresses, δ , U_e and pressure gradient, but independent of v.
- (3) An overlap layer which smoothly connects inner and outer regions. In this region both molecular and turbulent stresses and pressure gradient are important.

Considerably more information is obtained from the dimensional analysis and confirmed by experiment.

Inner layer: $U = f(\tau_w, \rho, \mu, y)$

$$U^+ = \frac{U}{u^*} = f(\frac{yu^*}{v})$$
 $u^* = \sqrt{\tau_w/\rho}$ Wall shear velocity

$$= f(y^+ = \frac{yu^*}{v})$$

 U^+ , y^+ are called inner wall variables.

Note that the inner layer is independent of δ or r_0 , for boundary layer and pipe flow, respectively.

 $\underbrace{U_e - U}_{velocity\ defect} = g(\tau_w, \rho, y, \delta) \quad \text{for } p_x = 0$

$$\frac{U_e - U}{u^*} = g(\eta)$$
 where $\eta = y / \delta$

Note that the outer layer is independent of μ .

Overlap layer: both laws are valid.

It is not that difficult to show that for both laws to overlap, f and g are logarithmic functions.

Inner region:

$$\frac{dU}{dy} = \frac{u^{*2}}{v} \frac{df}{dy^{+}}$$

Outer region:

$$\frac{dU}{dy} = \frac{u^*}{\delta} \frac{dg}{d\eta}$$

$$\frac{y}{u^*} \frac{u^{*2}}{v} \frac{df}{dy^+} = \frac{y}{u^*} \frac{u^*}{\delta} \frac{dg}{d\eta} \text{ ; valid at large } y^+ \text{ and small } \eta.$$

$$\underbrace{\int_{f(y+)}^{g(y+)} g(\eta)}_{g(\eta)} = \frac{y}{u^*} \frac{dg}{d\eta} \text{ ; valid at large } y^+ \text{ and small } \eta.$$

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Therefore, both sides must equal universal constant, κ^{-1}

$$f(y^+) = \frac{1}{\kappa} \ln y^+ + B = U/u^*$$
 (Inner variables)

$$g(\eta) = \frac{1}{\kappa} \ln \eta + A = \frac{U_e - U}{u^*} \quad \text{(Outer variables)}$$

 κ , A, and B are pure dimensionless constants.

$$\kappa$$
 = 0.41 Von Karman constant

Values vary somewhat depending on different exp. arrangements.

$$B = 5.5$$

The validity of these laws has been established experimentally as shown in Fig. 6-9, which shows the profiles of Fig 6-8 in inner-law variable format. All the profiles, except for the one for separated flow, are seen to follow the expected behavior. In the case of separated flow, scaling the profile with u^* is inappropriate since $u^* \sim 0$.

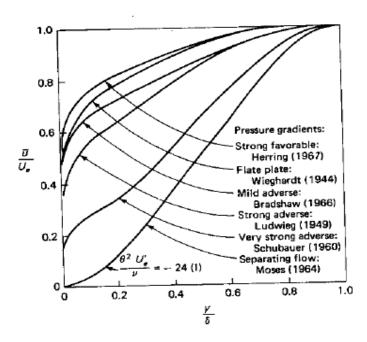


FIGURE 6-8
Experimental turbulent-boundary-layer velocity profiles for various pressure gradients. [Data from Coles and Hirst (1968).]

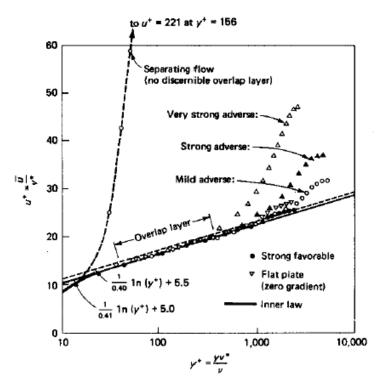


FIGURE 6-9 Replot of the velocity profiles of Fig. 6-8 using inner-law variables y^+ and u^+ .

Details of Inner Layer

Neglecting inertia and pressure forces in the 2D turbulent boundary layer equation we get:

The total shear stress is the sum of viscous and turbulent stresses. Very near the wall $y \rightarrow 0$, the turbulent stress vanishes. Sublayer region:

$$\lim_{y \to 0} \mu \left(\frac{dU}{dy} \right) - \rho \overline{u} \overline{v} = \mu \left(\frac{dU}{dy} \right)_{v=0} = \tau_w$$

From the inner layer velocity profile (note $u^* = \sqrt{\tau_w/\rho}$):

$$\left(\frac{dU}{dy}\right)_{y=0} = \frac{u^{*2}}{\nu} \frac{df(y^{+})}{dy^{+}} = \frac{\tau_{w}}{\mu}$$

$$\frac{df(y^{+})}{dy^{+}} = 1 \implies f(y^{+}) = y^{+} + C$$

No slip condition at y = 0 requires C = 0.

Sublayer: $U^+ = y^+$ valid for *y*⁺ ≤ 5 **Buffer layer:** Merges smoothly with the viscosity-dominated sub-layer and turbulence-dominated log-layer in the region $5 < y^+ \le 30$. Unified Inner layer: There are several ways to obtain composite of sub-/buffer and log-layers.

Evaluating <uv> near the wall shows that:

$$< uv > \sim y^3 \quad y \to 0$$

Several expressions which satisfy this requirement have been derived and are commonly used in turbulent-flow analysis, e.g., Spalding using the following assumptions:

- 1. Passes through y^+ = 0 at \overline{U}^+ = 0.
- 2. Is tangent at this point to $y^+ = \overline{U}^+$
- 3. Is asymptotic at large y^+ to $\overline{U}^+(y^+) = 2.5 \log y^+ + 5.5$
- 4. Fits the experimental points at intermediate y^+ values

$$\overline{U}^{+} = y^{+} - e^{-\kappa B} \left[e^{\kappa \overline{U}^{+}} - 1 - \kappa \overline{U}^{+} - \frac{\left(\kappa \overline{U}^{+}\right)^{2}}{2} - \frac{\left(\kappa \overline{U}^{+}\right)^{3}}{6} \right]$$

Fig. 6-11 shows a comparison of this equation with experimental data obtained very close to the wall. The agreement is excellent. It should be recognized that obtaining data this close to the wall is very difficult.

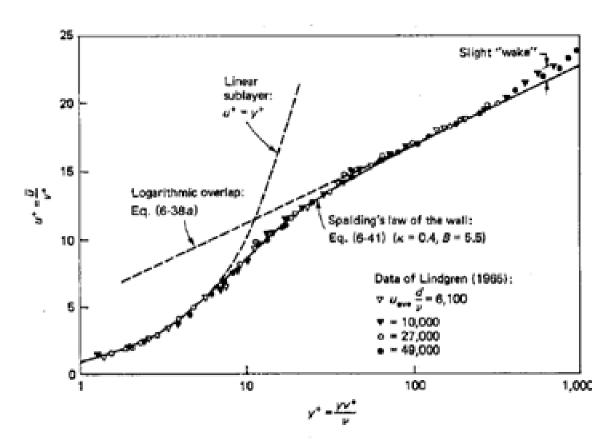


FIGURE 6-11
Comparison of Spalding's inner-law expression with the pipe-flow data of Lindgren (1965).

Outer Layer

Intermittency distinguishes BL outer region from channel and pipe flows, which reach fully developed condition vs BL spatially developing in streamwise direction. Also $\overline{V} \neq 0$, since $\overline{U_x} \neq 0$.

Outer flow scaling:

$$U_{\infty} - \overline{U}(y) = F\left(y, \delta, \rho, U_{\tau}, \frac{dP_{\infty}}{dx}\right) \neq f(v)$$

Using dimensional analysis:

$$\frac{U_{\infty} - \overline{U}(y)}{U_{\tau}} = U_{\infty}^{+} - \overline{U}^{+}(y) = F\left(\frac{y}{\delta}, \underbrace{\frac{\delta}{\rho U_{\tau}^{2}} \frac{dP_{\infty}}{dx}}\right) \quad (10)$$

equilibrium parameter

If δ replaced by $\delta_1 =$ Clauser (1954, 1956) equilibrium parameter β .

EFD suggests that $U_{\infty}^+ - \overline{U}^+(y)$ for BL with different $\frac{dP_{\infty}}{dx}$ but same β collapses under same profile, so called turbulent equilibrium.

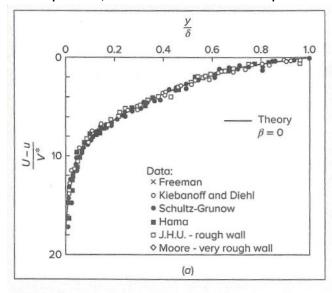
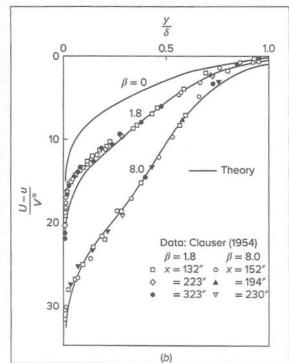


FIGURE 6-12 Equilibrium-defect profiles, as correlated by the Clauser parameter β and the theory of Mellor and Gibson (1966): (a) flat-plate data; (b) equilibrium adverse gradients.



The weakness of the Clauser approach to the outer layer is that the curves do not have a recognizable shape, which was resolved by Coles (1956) who notes the deviations of the velocity above the overlap layer when normalized by the maximum deviation at $y = \delta$ would be a single wake like function of y/δ only.

 $\overline{U}(y)$ deviates from log-law for $0.15 \le \frac{y}{\delta} \le 1$.

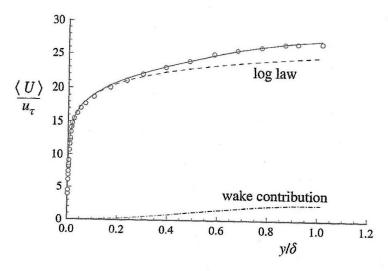


Fig. 7.28. The mean velocity profile in a turbulent boundary layer showing the law of the wake. Symbols, experimental data of Klebanoff (1954); dashed line, log law $(\kappa = 0.41, B = 5.2)$; dot-dashed line, wake contribution $\Pi w(y/\delta)/\kappa$ ($\Pi = 0.5$); solid line, sum of log law and wake contribution (Eq. (7.148)).

Imposing Eq. (10) to match log-law in the intermediate layer gives (neglecting pressure gradient):

$$\frac{1}{k}\ln y^{+} + B = U_{\infty}^{+} - F\left(\frac{y}{\delta}\right)$$

So that $F\left(\frac{y}{\delta}\right)=$ difference between outer flow U_{∞}^{+} and log-law.

For $y \ll \delta$, i.e., overlap region:

$$F\left(\frac{y}{\delta}\right) = U_{\infty}^{+} - \left[\frac{1}{k}\ln y^{+} + B\right] = \left[U_{\infty}^{+} - \frac{1}{k}\ln \delta^{+} - B\right] - \frac{1}{k}\ln\left(\frac{y}{\delta}\right)$$
$$\delta^{+} = U_{\tau} \,\delta/\nu$$

For y/δ in both overlap, and outer regions include wake function $W\left(\frac{y}{\delta}\right)$.

$$F\left(\frac{y}{\delta}\right) = \left[U_{\infty}^{+} - \frac{1}{k}\ln\delta^{+} - B\right] - \frac{1}{k}\ln\left(\frac{y}{\delta}\right) - \frac{\pi}{k}W\left(\frac{y}{\delta}\right) \quad (11)$$

 $rac{\Pi}{k}W\left(rac{y}{\delta}
ight)=$ amount that \overline{U}^+ rises above log-law in outer region beyond $y>0.15\delta$, and is equal to 0 in log law region. Π is a parameter and $F+rac{\Pi}{k}W$ is the difference between U_∞^+ and the log law extended into the outer layer.

Since, according to Eq. (10), $F\left(\frac{y}{\delta}=1\right)=0$:

$$W(1)\frac{\Pi}{k} = U_{\infty}^{+} - \frac{1}{k}\ln\delta^{+} - B$$
 (12)

And combining this result with Eqs. (10) and (11) gives the Coles "law of the wake":

$$\overline{U}^{+} = \frac{1}{k} \ln y^{+} + B + \frac{\Pi}{k} W \left(\frac{y}{\delta}\right)$$

$$= \frac{1}{k} \ln y^{+} + B + \frac{W\left(\frac{y}{\delta}\right)}{W(1)} \left(U_{\infty}^{+} - \frac{1}{k} \ln \delta^{+} - B\right)$$

i.e.,

$$\frac{W\left(\frac{y}{\delta}\right)}{W(1)} = \frac{\overline{U}^{+} - \frac{1}{k}\ln y^{+} - B}{U_{\infty}^{+} - \frac{1}{k}\ln \delta^{+} - B}$$

Representing the fractional velocity deficit relative to the log-law.

Empirical models:

$$\frac{\Pi}{k}W\left(\frac{y}{\delta}\right) = 2\frac{\Pi}{k}\sin^2\left(\frac{\pi}{2}\frac{y}{\delta}\right)$$

or

$$\frac{\Pi}{k}W\left(\frac{y}{\delta}\right) = \frac{1}{k}(1+6\Pi)\left(\frac{y}{\delta}\right)^2 - \frac{1}{k}(1+4\Pi)\left(\frac{y}{\delta}\right)^3$$

Where the latter is more accurate and W(1) = 2 is enforced in both models.

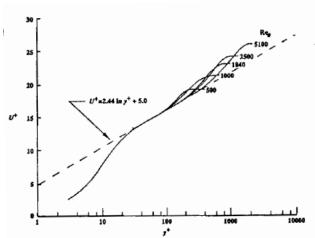


Fig 10. Comparison of mean-velocity profiles with logarithmic law at low Reynolds numbers. Boundary layer data from Purtell et al (1981).

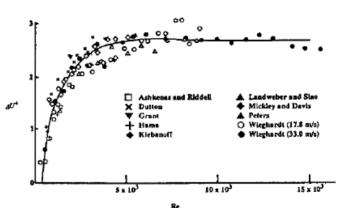
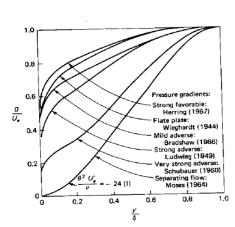


Fig 13. Reproduction of Coles' (1962) strength of the wake component in equilibrium turbulent boundary layers at low Reynolds numbers.



EXECUTE 6-8
EXPERIMENTAL TUrbulent-boundary-layer velocity profiles for various pressure gradients. [Data from Coles and Hirst (1968).]

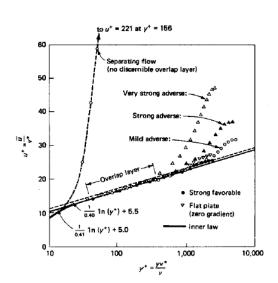


FIGURE 6-9
Replot of the velocity profiles of Fig. 6-8 using inner-law variables y^+ and u^+ .

According to Eq. (12),

$$\Pi = f(U_{\infty}^+, \delta^+) = f(x)$$

For zero-pressure gradient, it follows from

$$\frac{\delta}{x} = 0.37 Re_x^{-1/5}$$

That

$$Re_{\delta} = \frac{\delta U_{\infty}}{\nu} = 0.37 Re_{x}^{4/5}$$

$$Re_{\delta} = \frac{\delta U_{\infty}}{\nu} = 0.37 Re_{x}^{4/5}$$

$$\frac{U_{\infty} \delta}{\nu} = 0.37 \frac{U_{\infty} x}{\nu} Re_{x}^{-1/5}$$

Where $Re_x = xU_\infty/\nu$.

Using

$$U_{\tau}^2 = \frac{\tau_w}{\rho} = 0.0225 \frac{v^2}{\delta^2} Re_{\delta}^{7/4}$$

Gives

$$U_{\infty}^{+} = \frac{U_{\infty}}{U_{\tau}} = 5.89 Re_{x}^{1/10}$$

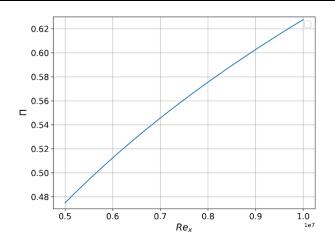
$$\delta^+ = 0.0628 Re_x^{7/10}$$

Recall Eq. (12):

$$W(1)\frac{\Pi}{k} = U_{\infty}^{+} - \frac{1}{k}\ln\delta^{+} - B$$

$$\Pi = \frac{k}{2} \left(5.89Re_{x}^{\frac{1}{10}} - \frac{1}{k} (-2.77 + 0.7\ln(Re_{x})) - B \right)$$

Which is slowly varying with x, e.g., with k=0.4, B=5.1 and Re_{x} ranging from 5×10^6 to 10^7 , Π varies from 0.48 to 0.63. Typically, $\Pi = 0.55$ is used.



Variation of Π vs Re_x .

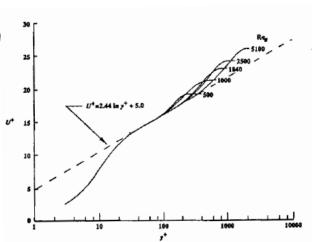
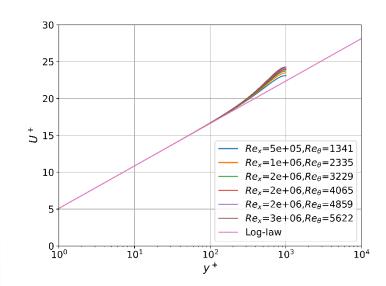


Fig 10. Comparison of mean-velocity profiles with logarithmic law at low Reynolds numbers. Boundary layer data from Purtell et al (1981).

Re_x	$Re_{\theta} = 0.037 Re_x^{4/5}$
5×10^{5}	8460
1×10^{6}	2334
1.5×10^{6}	3229
2×10^{6}	4605
2.5×10^{6}	4859
3×10^{6}	5622



Comparison of mean velocity profile with logarithmic law using:

$$\overline{U}^{+} = \frac{1}{k} \ln y^{+} + B + \frac{\Pi}{k} W \left(\frac{y}{\delta} \right)$$

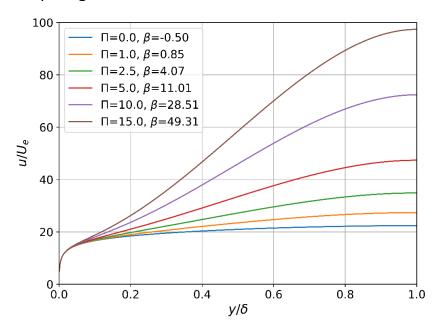
$$\Pi = \frac{k}{2} \left(5.89 R e_x^{\frac{1}{10}} - \frac{1}{k} (-2.77 + 0.7 \ln(Re_x)) - B \right)$$

$$k = 0.4, \quad B = 5.1$$

Alternative Π = wake parameter = $\Pi(\beta)$ including pressure gradient:

$$\Pi(\beta) = 0.8(\beta + 0.5)^{0.75} \rightarrow \text{(curve fit for data)}$$

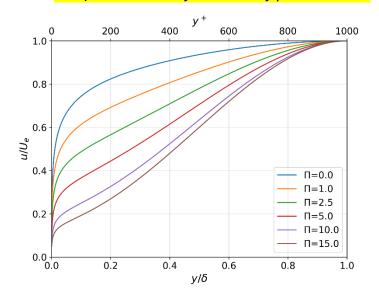
Note that for $\beta=0$ $\Pi=0.48$ and the agreement of Coles' wake law even for $\beta\neq$ constant. Bl's is quite good.

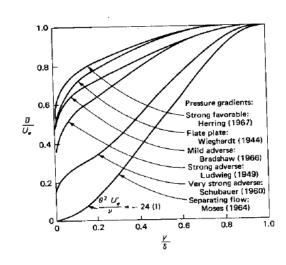


Turbulent velocity profiles computed from the Coles wall-wake formula

$$\overline{U}^{+} = \frac{1}{k} \ln y^{+} + B + \frac{\Pi}{k} W \left(\frac{y}{\delta} \right)$$

Assuming $\delta^+ = 1000$. The curve for $\Pi = 0$ is the pure law of the wall. Note that the plot starts at $y^+ = 1$ or $y/\delta = 0.001$.





Summary of Inner, Outer, and Overlap Layers

Mean velocity correlations

Inner layer:

$$U^+ = f(y^+)$$

$$U^{+} = U/u^{*}$$
 $y^{+} = y/u^{*}$ $u^{*} = \sqrt{\tau_{w}/\rho}$

Sub-layer: $U^+ = y^+$ for $0 \le y^+ \le 5$

Buffer layer: where sub-layer merges smoothly with

log-law region for $5 < y^+ \le 30$

Outer Layer:

$$\frac{U_e - U}{u^*} = g(\eta, \beta) \qquad \qquad \eta = y / \delta, \qquad \beta = \frac{\delta^*}{\tau_w} p_x$$

for $\eta > 0.1$

Overlap layer (log region):

$$U^{+} = \frac{1}{\kappa} \ln y^{+} + B \qquad \text{inner variables}$$

$$\frac{U_e - U}{u^*} = -\frac{1}{\kappa} \ln \eta + A \qquad \text{outer variables}$$

for $y^+ > 30$ and $\eta \le 0.3$

Composite Inner/Overlap layer correlation

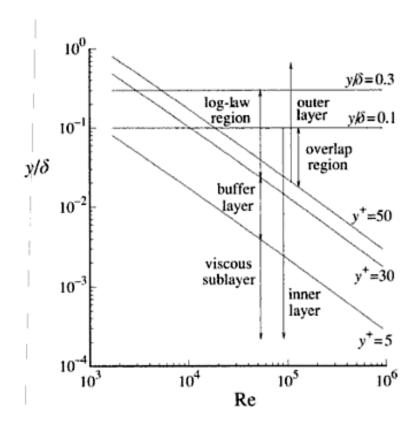
$$\overline{U}^{+} = y^{+} - e^{-\kappa B} \left[e^{\kappa \overline{U}^{+}} - 1 - \kappa \overline{U}^{+} - \frac{\left(\kappa \overline{U}^{+}\right)^{2}}{2} - \frac{\left(\kappa \overline{U}^{+}\right)^{3}}{6} \right]$$

Composite Overlap/Outer layer correlation

$$\overline{U}^{+} = \frac{1}{k} \ln y^{+} + B + \frac{\Pi}{k} W \left(\frac{y}{\delta} \right)$$

$$\frac{\Pi}{k}W\left(\frac{y}{\delta}\right) = 2\frac{\Pi}{k}\sin^2\left(\frac{\pi}{2}\frac{y}{\delta}\right)$$

Reynolds Number Dependence of Mean-Velocity Profiles and Reynolds stresses



- 1. Inner/overlap U^+ scaling shows similarity; extent of overlap region (i.e., similarity) increases with Re.
- 2. Outer layer for $p_x = 0$ may asymptotically approach similarity for large Re as shown by ΔU^+ vs. Re_{θ}, but controversial due to lack of data for Re_{θ} > 5 x 10⁴.

- 3. The normalized Reynolds stresses $\overline{u_l u_j}/k$, production-dissipation ratio and the normalized mean shear stress are somewhat uniform in the log-law region. Experiments in flat plate boundary layer, pipe and channel flow shows $k = 3.34 3.43 \ u^{*2}$ in lower part of log-law region.
- 4. Decay of $k \sim y^2$ near the wall.
- 5. Streamwise turbulence intensity $u^+ = \overline{u^2}/u^*$ vs. y^+ shows similarity for $0 \le y^+ \le 15$ (i.e., just beyond the point of k_{max} , $y^+ = 12$), but u^+ increases with Re_θ .

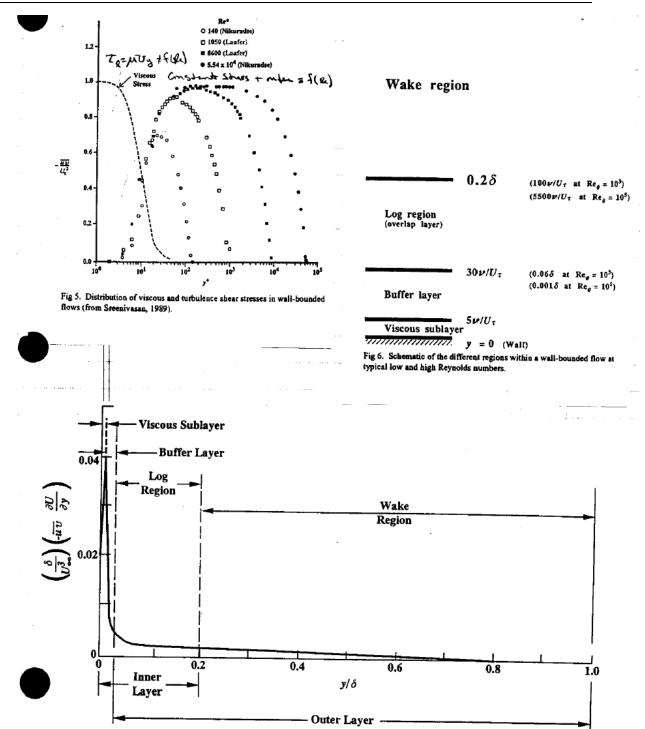


Fig 7. Normalized turbulence kinetic energy production rate as a function of normal distance from the wall. Data for a typical laboratory flat-plate boundary layer (from Kline et al, 1967).

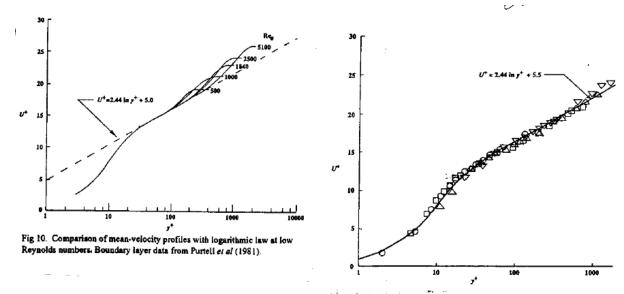
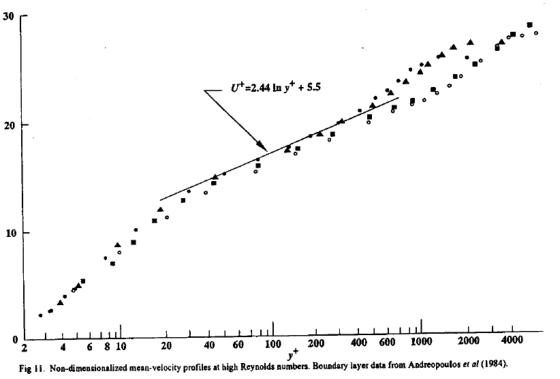


Fig 12. Mean-velocity profiles non-dimensionalized on inner variables. Channel flow data from Wei and Willmarth (1989).



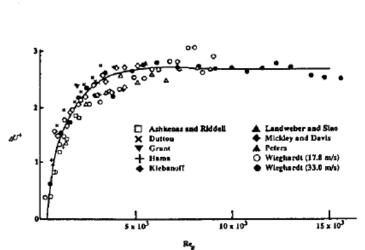
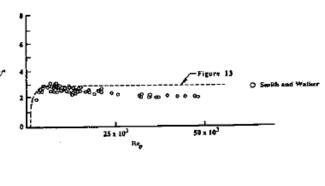


Fig 13. Reproduction of Coles' (1962) strength of the wake component in equilibrium turbulent boundary layers at low Reynolds numbers.



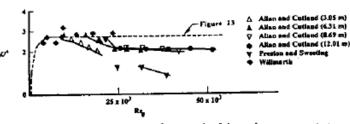


Fig 14. Reproduction of Coles' (1962) strength of the wake component at large Reynolds numbers.

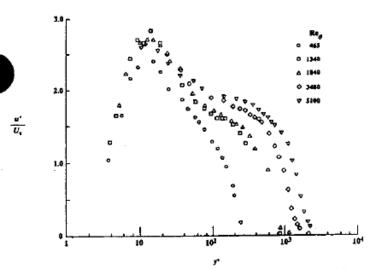


Fig 18. Variation of the distribution of turbulence intensity in wall variables with Reynolds number. Boundary layer data from Purtell et al (1981).

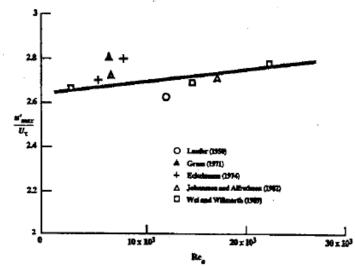


Fig 27. Peak value of u-turbulence intensity in two-dimensional channel flows. The plot, from five different experiments, demonstrates the effect of outer layer scales on inner-layer turbulence. Solid line represents the mean trend (from Bandyopadhyay, 1991).



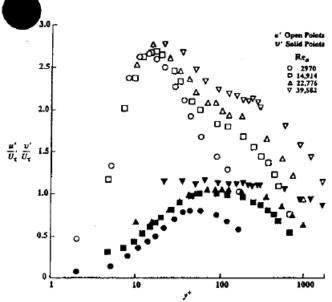


Fig 25. Profiles of turbulence intensity in streamwise direction (open points) and direction normal to wall (solid points), non-dimensionalized on inner variables. Channel flow data of Wei and Willmarth (1989).

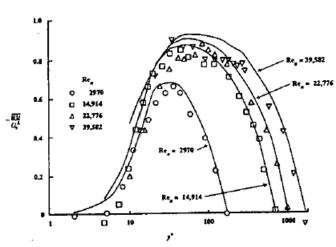


Fig 31. Reynolds stress profiles non-dimensionalized on inner variables. Channel flow data of Wei and Willmarth (1989) at four different Reynolds numbers. Solid line represents momentum balance calculations.

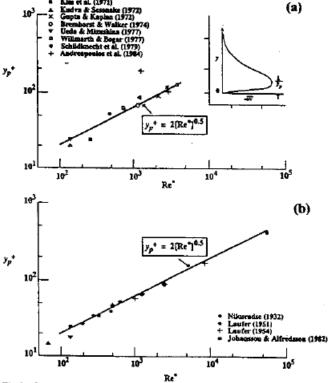
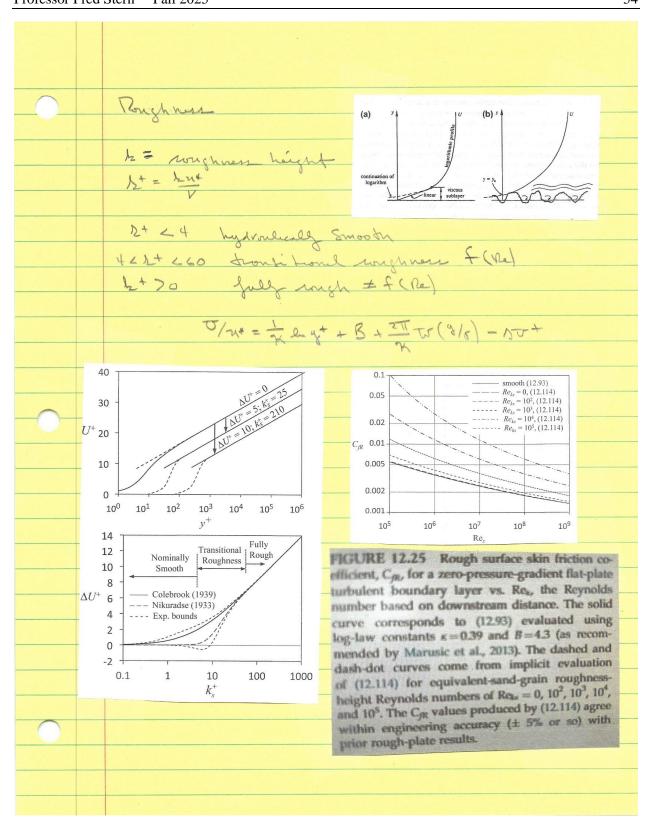


Fig 34. Location of peak Reynolds stress as a function of Reynolds number. Data compiled by Sreenivasan (1988) from various wall-bounded flow experiments. Solid lines are least-square fit: (a) Directly measured Reynolds stress; (b) Computed from measured mean vetocity. The lowermost two data points correspond to the critical layer position in typical transitional flows.



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